# PSW-002 

## Fiber Optic Polarization Switch



## User Guide

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## PSW-002 User Guide

## SAFETY CONSIDERATIONS

The following safety precautions must be observed during operation of this product. Failure to comply with these precautions or with specific warnings elsewhere in this manual violates safety standards of design, manufacture, and intended use of the product. General Photonics assumes no liability for customers' failure to comply with these requirements.

## Before operation, the user should inspect the product and review the manual carefully.

Use only in a safe work environment in terms of temperature, humidity, electrical power and risk of fire or shock. The product is designed for indoor use. Avoid exposure to liquids or water condensation. Provide adequate ventilation for cooling.

Operate the product on a stable surface. Avoid excess vibration.
Standard laser safety procedures should be followed during operation.

Never look into the light source fiber connector when the light source is turned on. THE OUTPUT LI GHT FROM A HIGH POWER LASER IS HARMFUL TO HUMAN EYES. Follow industry standard procedures when operating a high power laser source.

## PSW-002 User Guide

Section 1.0 Overview ..... 7
1.1 Principle of Operation ..... 7
Section 2.0 Features ..... 9
2.1 Optical Features ..... 9
2.2 Electrical Features ..... 9
2.3 Switch Timing ..... 11
2.4 Dimensions and Mounting Holes ..... 13
Section 3.0 Operation Instructions ..... 14
3.1 Unpacking ..... 14
3.2 Operation ..... 14
Section 4.0 Specifications ..... 15
Optical ..... 15
Electrical ..... 15
Physical and Environmental ..... 15
Appendices ..... 17
Appendix 1.0 Driver Board (Optional) ..... 17
Driver Board Specifications ..... 17
Board Diagram ..... 18
Setup ..... 19
Power Supply/Control Signal Guidelines ..... 19

## PSW-002 User Guide

## Section 1.0 <br> Overview

The PSW-002 is a miniature polarization switch that rotates the input polarization state by a fixed angle, either $45^{\circ}$ or $90^{\circ}$. It is available with either single mode (SM) fiber or polarization maintaining (PM) fiber pigtails. The switching of the polarization state is achieved using an external control current supply. The PSW-002 is compact and can be mounted on a PCB Applications include polarization diversified detectors and sensors, polarization multiplexing, polarization modulation, polarization metrology, polarization mode dispersion (PMD) monitoring, coherent optical communications, and other polarization related applications.


Figure 1 PSW-002 polarization switch

### 1.1 Principle of Operation

The PSW-002 performs polarization state transformations on a signal traveling in optical fiber. Using Poincaré sphere representation, the PSW-002 transforms the input polarization state along the equi-ellipticity contours that are represented by latitude lines. The $90^{\circ}$ and $45^{\circ}$ PSW002 devices rotate the polarization state by a half (1/2) circle or quarter circle ( $1 / 4$ circle), respectively, along the latitude line on which the input polarization state falls. Figure 2 a shows the two output SOPs of a $90^{\circ}$ PSW resulting from different input polarization states. In the first case, the input SOP is linear (on the equator); the two output SOPs will be $180^{\circ}$ apart on the circle defined by the equator (points $A$ and $B$ in the diagram). In the second case, the input SOP is elliptical; the two output SOPs (points C and D) will be $180^{\circ}$ apart on a smaller circle corresponding to the latitude line on which the input SOP falls. If the input polarization state is circular (north or south poles of the sphere), the latitude circle collapses to a point, so the output SOP will still be circular.

Figure 2 b shows a similar example for a $45^{\circ} \mathrm{PSW}-002$. In this case, points $A$ and $B$ and points $C$ and $D$ are $90^{\circ}$ from each other on their respective circles.


Figure 2 Examples of Poincaré sphere representations of output polarization states of $90^{\circ}$ and $45^{\circ}$ PSW-002s for 2 different cases:
Case 1: Linear input SOP $\rightarrow$ output states $A$ and $B$
Case 2: Elliptical input SOP $\rightarrow$.output states $C$ and $D$
Please note that the rotation angle with respect to the $S_{3}$ axis is generally not the same as the solid angle with respect to the origin of the sphere unless the rotation is on the equator $\left(\mathrm{S}_{3}=\right.$ 0 ). In Figure $2 b$, both sets of output states (points $A$ and $B$ and points $C$ and $D$ ) are rotated $90^{\circ}$ from each other with respect to the $S_{3}$ axis; however, the solid angle between points $C$ and $D$ with respect to the origin of the sphere is not $90^{\circ}$. Instead, it is some angle $a$, whose value depends on the $S_{3}$ coordinate of the input SOP.

For a PSW-002 with PM fiber pigtails, an input state aligned to either the slow or fast axis of the input fiber will result in a polarization transformation on the equator of the Poincaré sphere. With a slow-axis aligned input, a $90^{\circ}$ PM PSW-002 switches the output polarization state between alignment with the slow and fast axes of the output PM fiber. With a slow-axis aligned input, a $45^{\circ}$ PM PSW switches the state of its output light between slow-axis aligned and $45^{\circ}$ from the slow axis at the point where it launches into the output PM fiber.

# PSW-002 User Guide 

## Section 2.0 <br> Features

### 2.1 Optical Features



Figure 3 PSW-002 input and output pigtails

Figure 3 shows the input/output pigtails for the PSW-002. For devices with SM fiber pigtails, the input and output pigtails are interchangeable. Devices with PM fiber pigtails should be used with the designated input/output configuration. There is also an option to add a slow-axis aligned polarizer at the PSW input port to improve output PER and rotation angle accuracy. Devices with the polarizer included will not work as a polarization switch if the pigtails are reversed.

Fiber connectors can be FC/PC, FC/APC, SC/PC, or SC/APC per customer specification. Before each connection, fiber connectors should be cleaned using industry standard fiber connector cleaning methods. For PM pigtailed PSW-002s, the input connector alignment is also very important. For devices without an input polarizer, any connector misalignment to the input connector can affect output PER and rotation angle accuracy.

Fiber pigtails should be handled carefully. Excessive force on fiber pigtails may degrade performance or damage the device.

### 2.2 Electrical Features

The PSW-002 requires a bipolar electrical current to perform polarization state switching. Without a drive current, the PSW-002 will not rotate the input polarization state, and its insertion loss will be slightly higher. In laboratory applications, the PSW-002 can be driven by a function generator or a DC power supply. The PSW-002 has two electrical connection pins for the electrical control signals. Its electrical equivalent circuit is shown in Figure 4, where $L_{c}$ is an inductor and $R_{c}$ is a resistor.


Figure 4 PSW-002 equivalent electrical circuit

Voltage/Current Guidelines:
The PSW-002 requires a certain level of current and voltage to switch from one output state to another (switching voltage/current), but once it has switched, it can maintain its state with a lower voltage/current (latching voltage/current).

|  | Voltage | Current |
| :--- | :--- | :--- |
| Switching | $2-3 \mathrm{~V}$ | $<130 \mathrm{~mA}$ |
| Latching | $1.5-2 \mathrm{~V}$ | $<80 \mathrm{~mA}$ |

A typical drive signal might look like:


Figure 5 Drive signal diagram
$\mathbf{V}_{\mathrm{s}}=$ switching voltage
$\mathrm{V}_{\mathrm{L}}=$ latching voltage
$\mathrm{T}_{\mathrm{s}}$ = time switching voltage is applied
Lowering the control voltage to the latching voltage to maintain the current output state improves the stability of the output state because it reduces device heating, which can affect the rotation angle. It is generally recommended to use a drive signal pattern like the one shown in Figure 5, especially if the PSW-002 is to remain in one state or the other for relatively long periods of time.

## PSW-002 User Guide

The output SOP depends on the polarity of the voltage between the two pins. For a PM fiber PSW-002 with a slow-axis aligned input, the correspondence is as follows.


Figure 6 PSW-002 pinout

| PIN1 | PIN2 | Output SOP |
| :--- | :--- | :--- |
| - | + | Fast axis <br> $45^{\circ}$ from slow axis $\left(90^{\circ} \mathrm{PM}\right.$ PSW PM PSW) |
| + | - | Slow axis |

### 2.3 Switch Timing

A typical switching response is shown in Figure 7, where the upper trace is the synchronization output waveform from a function generator, and the lower trace is the PSW-002 output power after a polarizer. A function generator with output voltage set at $\pm 2 \mathrm{~V}$ is used as the PSW-002 driver. The time scale (horizontal axis) is $50 \mu \mathrm{~s} /$ division.

As shown in Figure 7, when a step function waveform voltage is applied to the PSW-002, there is an initial delay of $\sim 75 \mu \mathrm{~s}$. The rise time ( $10 \%-90 \%$ ) of the switch is also on the order of a few 10 s of $\mu \mathrm{s}$. The total switching time is $\sim 100 \mu \mathrm{~s}$.

PSW-002 User Guide


Figure $\mathbf{7}$ Switching speed of PSW-002 under a-2 to $+\mathbf{2 V}$ voltage step

## PSW-002 User Guide

### 2.4 Dimensions and Mounting Holes

The PSW-002 has one mounting hole on its bottom surface, between the electrical pins. Package dimensions and electrical pin and mounting hole locations are given below.

Electrical pins are 0.5 mm in diameter.


Figure 8 Dimensions and mounting hole information All dimensions given in inches.

## Section 3.0

## Operation Instructions

### 3.1 Unpacking

Inspect PSW-002 for any physical damage due to shipping and transportation. Contact carrier if any damage is found. Check the packing list to see if any parts or accessories are missing.

Packing List

| Item \# | Description |
| :--- | :--- |
| 1 | PSW-002 |
| 2 | User Guide |
| 3 | Electrical cable (only for devices with driver board) |

### 3.2 Operation

1. Make optical connections. For PM PSWs, do not reverse input and output connectors.
2. Connect the two electrical leads to an electrical driver such as a function generator, analog output board, or DC power supply, as shown schematically in Figure 9. Make sure that the electrical driver is capable of driving an inductive load.
3. Power on the driving circuit.


Figure 9 Examples of basic driver setups. A function generator can be used to drive the PSW for periodic switching, while a DC power supply may be sufficient for occasional switching.
Note that this diagram shows only switching voltages. Once the device has switched state, the voltage can be lowered to the latching voltage to maintain the output state.

## PSW-002 User Guide

## Section 4.0

## Specifications

## Optical

| Operating Wavelength | $1550 \pm 30 \mathrm{~nm}$ or $1310 \pm 30 \mathrm{~nm}$ |
| :--- | :--- |
| Polarization Rotation <br> (at $\lambda_{c}, 23^{\circ} \mathrm{C}$ ) | $45 \pm 0.5^{\circ}$ or $90 \pm 0.5^{\circ}$ |
| Polarization Rotation <br> (all wavelengths, all temps) | $45 \pm 5^{\circ}$ or $90 \pm 5^{\circ}$ |
| Rotation Angle Temperature <br> Dependence | -0.1 degree ${ }^{\circ} \mathrm{C}$ for $45^{\circ}$ version <br> -0.2 degree $/{ }^{\circ} \mathrm{C}$ for $90^{\circ}$ version |
| Switching Time | $100 \mu \mathrm{~s}$ typical |
| Insertion Loss | $<0.5 \mathrm{~dB}$ |
| Return Loss | $>55 \mathrm{~dB}$ |
| Extinction Ratio ${ }^{1}$ | $>18 \mathrm{~dB}$ for PM model |
| Optical Power Handling | 300 mW |

Note: Values referenced without connectors.

1. Both output states of $90^{\circ} \mathrm{PM}$ PSW with input polarizer at $23^{\circ} \mathrm{C}$.

## Electrical

| Switching Current | $<130 \mathrm{~mA}$ |
| :--- | :--- |
| Switching Voltage | 2.5 V |
| Latching Current | $\sim 80 \mathrm{~mA}$ |
| Latching Voltage | 1.5 to 2 V |

Physical and Environmental

| Fiber Type | PM Panda, SMF-28 or compatible |
| :--- | :--- |
| Operating Temperature | $0^{\circ} \mathrm{C}$ to $50^{\circ} \mathrm{C}$ |
| Storage Temperature | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |
| Dimensions | $1.57^{\prime \prime}(\mathrm{L}) \times 0.69^{\prime \prime}(\mathrm{W}) \times 0.53^{\prime \prime}(\mathrm{H})$ |
| Weight | 30 g typical |

## PSW-002 User Guide

## Appendices

## Appendix 1.0 Driver Board (Optional)

General Photonics offers an optional driver board to simplify use of the PSW-002. The board generates the recommended switching/latching voltages (see Figure 5), allowing the user to control the output state using simple TTL levels.

Note that the control signal for the board is TTL levels, not pulses. For a PM fiber PSW-002 with a slow-axis aligned input, the correspondence is as follows.

| TTL Level | PIN1 | PIN2 | Output SOP |
| :--- | :--- | :--- | :--- |
| High | - | + | Fast axis <br> $45^{\circ}$ from slow axis $\left(40^{\circ}\right.$ PM PSW PSW) |
| Low | + | - | Slow axis |



Figure 10 PSW-002 on driver board

## Driver Board Specifications

| Electrical connector | IDC 6-pin connector (2x3 pins), cable provided |
| :--- | :--- |
| Power supply | $+8 \sim+15 \mathrm{VDC} / 0.2 \mathrm{~A}$ |
| Control signal | TTL logic level 0-5V |
| Maximum switching rate | 1 kHz (1ms per state) |
| LED indicators | Drive logic high (red) and low (green) |
| Dimensions | $1.50^{\prime \prime}(\mathrm{L}) \times 1.50^{\prime \prime}(\mathrm{W}) \times 0.58^{\prime \prime}(\mathrm{H})$ |
| Mounting holes | $4 \times \varnothing 2 \mathrm{~mm}$ |

## Board Diagram



Figure 11 PSW driver board dimensions and pinout
The PSW driver board has 4 mounting holes located at the corners of the board, as shown above.

A 6-pin electrical connector is used to connect the power supply and control signal. A connection cable is provided. The connector pinout and corresponding connection cable color code are as follows:

## PSW-002 User Guide

Table 1 PSW driver board cable pinout

| Pin \# | Symbol | Wire Color | Function | Description |
| :--- | :--- | :--- | :--- | :--- |
| 1 | GND | Brown | Board ground |  |
| 2 | GND | Red | Board ground |  |
| 3 | PS | Orange | Polarization <br> switching | Logic signal, TTL compatible <br> Low = polarization state A <br> High = polarization state B |
| 4 | PWR | Yellow | Power input | $8 \sim 15 \mathrm{VDC} / 200 \mathrm{~mA}$ |
| 5 | GND | Green | Board ground |  |
| 6 | GND |  | Board ground |  |

The connection cable is shown below.


Figure 12 PSW driver board electrical cable

## Setup

1. Connect optical input and output to PSW-002.
2. Connect electrical cable to board.
3. Make sure power supply voltage and current are set at appropriate levels (8 to 15VDC/200 mA).
4. Connect control signal.
5. Power on power supply.

## Power Supply/Control Signal Guidelines

## Power Supply

The PSW-002 driver board will accept a power supply voltage anywhere between 8 and 15 V , but it is generally better to use a lower voltage if possible (i.e. closer to 8 V ).

## Control Signal

Voltage ranges:

| TTL Level | Nominal | Range |
| :--- | :--- | :--- |
| High | 5 V | $3-5 \mathrm{~V}$ |
| Low | 0 V | $0-1 \mathrm{~V}$ |

Current requirement: $<1 \mu \mathrm{~A}$
Maximum switching rate: 1 kHz (1 ms per output state)

